



ADVANCED CONTROL SYSTEMS CORPORATION

# SMC-32

## Stepping Motor Controller/Driver

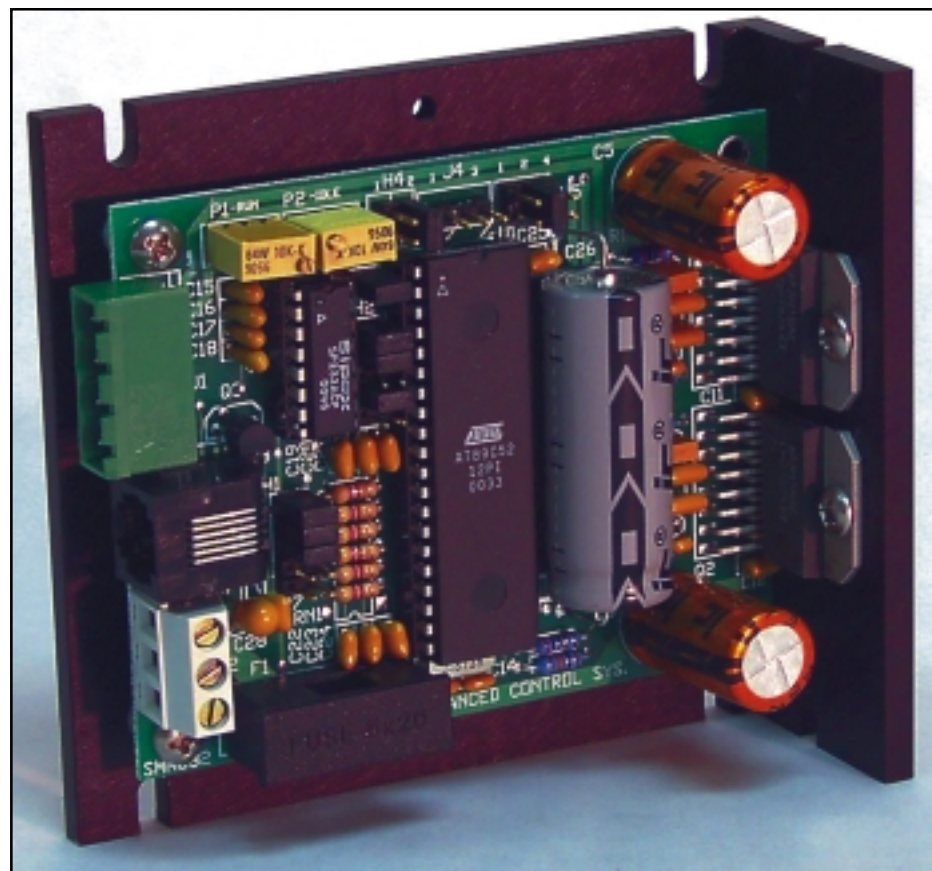
### DESCRIPTION:

SMC-32 is an integrated stepping motor controller/driver unit, suitable for OEM applications. It can control any 4, 6, or 8 lead two/four phase stepping motor with continuous currents up to 3A (6A peak) and at motor supply voltages up to 48V.

The SMC-32 is available in two standard versions and customized versions for specific applications.

The SMC-32A version is an addressable controller, controlled by the host computer via RS-232 communication port.

The SMC-32B version functions as an independent intelligent controller with program stored in the controller's nonvolatile memory.



Photograph above: SMC-32 Stepping Motor Controller/Driver

### FEATURES:

- ☐ Low Cost
- ☐ High reliability
- ☐ Small Size (4" x 3.65" x 1.5")
- ☐ Control of two/four phase motors to 3A/phase
- ☐ Stepping rates up to 50,000 steps/sec
- ☐ Full step and ministepping modes
- ☐ Up to 16.7 million steps per move
- ☐ Adjustable current reduction in idle
- ☐ Motor current shut-off by switch or control command
- ☐ Nonvolatile memory for motion control parameters and programs
- ☐ Manual jog control inputs
- ☐ Motor position always available
- ☐ Two limit inputs and home input
- ☐ Internal expansion communication bus for up to 32 axis control

# SMC-32

## SPECIFICATIONS:

### ELECTRICAL:

|                                |   |
|--------------------------------|---|
| <b>Motor Voltage:</b>          | +12 to +48VDC/up to 2Amp Req.   |
| <b>Drive Current:</b>          | .125 to 3A/Phase; trim pot adjustable.                                |
| <b>Logic Voltage:</b>          | +5VDC $\pm 5\%$ : 50mA.   |
| <b>Idle Current:</b>           | 0 to 3A/Phase; trim pot adjustable.                                   |
| <b>Stepping Mode:</b>          | Full step, two phases on; full step, one phase on.                    |
| <b>Ministepping:</b>           | Two, three, four, five, six or eight ministepping per full step.      |
| <b>Serial Communication:</b>   | RS232; 2400, 9600, 19200, 57600 baud.                                 |
| <b>Byte Structure:</b>         | 10 bit ASCII characters; start bit, 8 data bits, stop bit, no parity. |
| <b>Control Inputs:</b>         | Limit +, Limit -, Home, Jog+, Jog-, Current off.                      |
| <b>Address Inputs:</b>         | Five – 0 to 31 address range (SMC-32A version only).                  |
| <b>General Purpose Inputs:</b> | Five – programmable (SMC-32B version only).                           |
| <b>Inputs/Outputs:</b>         | Inputs TTL, Outputs TTL 20mA sink.                                    |

### MECHANICAL:

|                             |  |
|-----------------------------|--|
| <b>Physical Dimensions:</b> | 4.0" x 3.65" x 1.5"<br>Weight: 8.7 oz. (.25 kg.) |
| <b>Heat Dissipation:</b>    | Integral heat sink, L shaped.                    |

### ENVIRONMENT:

|                               |  |
|-------------------------------|--|
| <b>Storage Temperature:</b>   | -40 to 250 degrees F<br>-40 to 125 degrees C |
| <b>Operating Temperature:</b> | -20 to 140 degrees F<br>-28 to 60 degrees C  |
| <b>Thermal Shutdown:</b>      | Ts = 300 degrees F<br>150 degrees C          |
| <b>Humidity:</b>              | <95% non-condensing                          |

## INSTRUCTION SET:

### MOTION EXECUTE:

|           |  |
|-----------|--|
| M $\pm$ n | MOVE for "n" steps at constant stepping rate.          |
| I $\pm$ n | INDEX for "n" steps using preset rates and ramps.      |
| G $\pm$ n | GO to Absolute position using present rates and ramps. |
| H $\pm$   | Move to HOME position at constant stepping rate.       |
| F         | FINISH Function: Motor decelerates and stops.          |
| Q         | QUIT Function: Motor stops stepping immediately.       |

### DATA ENTER/EXAMINE:

|   |  |
|---|--|
| C | Enter/Examine CONSTANT RATE OF STEPPING.                           |
| J | Enter/Examine JOG RATE OF STEPPING.                                |
| V | Enter/Examine HIGH SPEED RATE OF STEPPING.                         |
| R | Enter/Examine RAMP INDEX (Acceleration/Deceleration) OF THE MOTOR. |
| D | Load DEFAULT motion parameters.                                    |
| X | Examine motion status (stepping or stopped).                       |
| E | Examine limits and home inputs.                                    |
| L | Enable/Disable or examine limit interrupts.                        |
| W | Turn On/Off or examine motor winding Current.                      |
| P | Examine or set absolute position.                                  |
| S | Save motion indexes to NV memory.                                  |
| T | Test message.  |

### PROGRAM CONTROL: (SMC-32B VERSION ONLY):

|    |                                |
|----|--------------------------------|
| OM | Output Message.                |
| OL | Output Level.                  |
| OP | Output Pulse.                  |
| WM | Wait for motor to stop.        |
| WI | Wait for Input.                |
| JI | Jump to program line on input. |
| JL | Jump to program line.          |
| RS | Repeat program loop start.     |
| RE | Repeat loop end.               |
| RR | Repeat loop reset.             |
| DL | Delay                          |

*For further information on this or other products, please call our Sales Department*



## ADVANCED CONTROL SYSTEMS CORPORATION

35 Corporate Park Drive, Pembroke, Massachusetts 02359  
(781) 829-9228 Fax: (781) 829-9875 [www.acsmotion.com](http://www.acsmotion.com)